

**Consultation:** The Future of Remote Pilot Competency in the Specific Category



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# **Consultation Structure**

The CAA recognises the impact of restructuring remote pilot competency training on Recognised Assessment Entities (RAEs) and the UK UAS industry. This purpose of this consultation is to gather views from key stakeholder groups including RAEs, Remote Pilots, and Operators early in the policy development process.

Given the length of the document being consulted on the CAA has chosen a mechanism of capturing feedback that allows for the simplest interrogation of the data.

To that end, each line within the consultation document is sequentially numbered. If you identify an area you wish to provide feedback, please include the line number as a reference for each comment that you wish to provide.

#### 1 **CHAPTER 1**

#### 2 Introduction

#### 3 Background

- 4 In July 2022, the Civil Aviation Authority (CAA) formed an internal working group to
- develop a framework of new remote pilot (RP) competencies for the Specific category. The 5
- 6 working group, led by the CAA Remotely Piloted Aircraft System (RPAS) Policy Team,
- 7 bought together experts from RPAS Policy, RPAS Sector, Airspace, Air Traffic
- 8 Management and Aerodromes (AAA), and the CAA Medical Teams.
- 9 The formation of the RP Competency Working Group (RPCWG) was driven by two primary 10 requirements:
- 11 Review the current RP competency training system to assess its fitness to 12 provide safe UAS operations.
  - Establish the future competency requirements needed to enable more complex and scalable UAS operations.

#### 15 **Purpose**

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16 The purpose of this document is to share the CAA's thinking on the future of RP 17 competency and receive early feedback from all stakeholders through structured 18 consultation. It is important to consider this document in the context of future UAS 19

operations that may not currently routinely be approved by the CAA and not as

20 comparison to the current CAP 722B.

#### 21 Analysis

- 22 The RPCWG carried out a comprehensive analysis of RP competency training both
- 23 current state and future requirements. Intelligence from the UAS Safety Review Panel,
- 24 which takes in data from the Air Accidents Investigation Branch (AAIB) and European Co-
- 25 ordination Center for Accident and Incident Reporting Systems 2 (ECAIRS2), was used to
- 26 review the current safety risks directly linked to RP competency and training to identify
- 27 improvement areas.
- 28 Analysis of future RP competency requirements considered best practice from numerous
- 29 sources such as the International Civil Aviation Organisation (ICAO), the Joint Authorities
- for Rulemaking on Unmanned Systems (JARUS), the European Union Aviation Safety 30
- 31 Agency (EASA), the Civil Aviation Safety Agency (CASA), as well as drawing on manned
- 32 aviation best practise. Where policy did not exist, it was developed in accordance with
- 33 CAA regulatory principles and peer reviewed by the RPCWG and the wider CAA.

30	The result of	the analysis revealed some locus areas for future development.
36 37 38	١	The current General Visual Line of Sight Certificate (GVC) is limited by the /LOS condition and therefore its scope to expand with future needs is also imited
39 40		Any new RP competency training will need to work with UK Specific Operational Risk Assessment (SORA) once it has been implemented
41 42		The complexity of future training will require the current RAE structure to be nore adaptable to future needs
43 44 45 46	ř E	The number of different types of UAS and operations means that it not practical to implement a 'type rating' system. Instead, operators and Original Equipment Manufacturers (OEM) will propose an acceptable level of type specific training during the application for an Operational Authorisation (OA).

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#### <sup>47</sup> Conclusion

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After considerable analysis including feedback from RAEs, the RPCWG concluded that the level of required RP competency falls largely into the following operational boundaries:

#### <sup>50</sup> Visual Line of Sight (VLOS) Operations

- 51 Simple Unmanned Aircraft System (UAS) operations that can be undertaken using a basic
- 52 Pre-Determined Risk Assessment (PDRA) when VLOS is used as the primary method of
- 53 deconfliction.

#### <sup>54</sup> Complex VLOS and localised beyond visual line of sight (BVLOS) operations

- 55 VLOS operations that are complex and require a higher level of competency, for example,
- 56 flying close to uninvolved people. Localised BVLOS operations that are not affected by en-
- 57 route threats such as changing weather or integration with other air users.

#### 58 BVLOS En-route Operations

- 59 BVLOS operations that are complex and are subject to en-route threats such as other
- 60 traffic, changing weather, changing airspace, and landing at a remote destination.

#### <sup>61</sup> BVLOS Highly Complex Operations

- 62 BVLOS operations as above but require specific additional competencies such as
- 63 integrating with Instrument Flying Rules (IFR) traffic, multi crew cooperation and operating64 in and out of licenced aerodromes.
- 65 The RPCWG also concluded that the level of operational risk, for example the SORA
- 66 SAIL, does not always correlate with the required competency. For example, a flight in
- 67 controlled airspace requires specific competencies, however it is not necessarily higher68 risk than a flight conducted in uncontrolled airspace.
- Therefore, the proposed training framework reflects an operation centric and modularapproach.

73	RPCWG Workstreams
74	The RPCWG project has four main workstreams which are:
75 76	<ul> <li>Rulemaking to establish RAEs under an improved legal basis such as the UK Regulation (EU) 2018/1139, the Basic Regulation</li> </ul>
77	<ul> <li>Establishing medical standards for RPs in the specific category</li> </ul>
78	<ul> <li>Developing a framework for the future of RP competency</li> </ul>
79	<ul> <li>Developing the supporting RP competency policy, AMC, and GM</li> </ul>
80	Rulemaking to Establish RAEs under an Improved Legal Basis
81 82 83 84 85	RAEs for RP competency are currently established under article 268 of the Air Navigation Order (ANO). In March 2022 the RPAS Policy Team began a rule making task with the Department for Transport (DfT) to define RAEs as specific entities in law. The CAA recommended that RAEs be established under UK Regulation (EU) 2019/947, the Implementing Regulation, (where the majority of UAS regulation now sits).
86	This will benefit the CAA and RAEs by:
87 88	<ul> <li>making the responsibilities of RAEs, when discharging their duty on behalf of the CAA, clear and legally binding</li> </ul>
89 90 91	<ul> <li>allowing the CAA to respond to the future needs of industry by establishing third party entities to issue certificates on behalf of the CAA rather than providing reports under the ANO</li> </ul>
92 93 94	<ul> <li>for Acceptable Means of Compliance and Guidance Material (AMC &amp; GM) to be developed in a transparent manner, including full public consultation where applicable</li> </ul>

- In October 2022, the CAA wrote to all RAE's and published the above proposal as a full
  public consultation the results of which can be found <u>here</u>. We received 10 responses,
- 97 most of which welcomed the proposed changes. Some respondents requested more98 explanation of the proposed changes which this document seeks to address.
- 99 In December 2022, the RPAS policy team submitted our Opinion and Instruction
- 100 Document (OID) to the DfT. The DfT and CAA are considering which legal powers are
- 101 most appropriate for expanding the scope of RAEs and will report out in due course.

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**CHAPTER 2** 

**RPCWG Workstreams** 

#### <sup>102</sup> **RAE Structure Review**

Delivery of future RP training by RAEs will be more complex and potentially require more resources. The CAA anticipates that not all RAEs will want to conduct advanced training courses depending on their specific business model. Therefore, the CAA is proposing to introduce two tiers of RAE for RP competency:

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RAE – Basic Competency (BC)

108 • RAE – Advanced Competency (AC)

BC RAEs will be approved to deliver RP training including the A2CofC, GVC and the
 Basic Remote Pilot Certificate (RPC-B). The oversight regime for this RAE type will remain
 largely the same as currently detailed in CAP 722B.

- AC RAEs will be approved to deliver all the above courses including advanced RP
- training. The oversight regime for this type of RAE may be more stringent than for a RAE
- <sup>114</sup> BC, proportional to the increased safety risk of delivering complex RP training for CAA.
- <sup>115</sup> After the CAA and DfT have completed the regulatory review of the legal basis for RAEs,
- the CAA will publish new AMC &GM for public consultation detailing the above structure,
- requirements, and process to make an application under the new scheme.

#### <sup>118</sup> Establishing Remote Pilot Medical Standards in the Specific Category

- 119 For the majority of current UAS operations, a declaration of RP fitness to fly is
- 120 proportionate to the safety risk. Many OA holders have implemented more stringent
- 121 requirements as part of their safety management system (SMS) which is to be
- 122 commended. In the future, RPs are likely to be undertaking operations in more complex
- 123 airspace and over areas of increased ground risk.
- 124 The RPCWG engaged with the CAA Medical Team to establish what, if any, medical 125 standard should be applied to more complex operations in the Specific category.
- 126 Key aims for the study were:
- Proportionality To develop medical standards that are proportionate to the risk of UAS operations, reflecting the capabilities these systems have for improved safety over manned aviation. This may include software which defaults to autopilot when user input is removed, collision avoidance and always-on airspace restrictions.
- Longevity To ensure that UAS medical standards can survive the pace of development in this sector and don't stifle future growth. Any standard needs to be both justified and reflect technology which can be applied to overcome any loss of capability from illness or injury.

136 Cross Certification – To minimise regulatory burden and reflect the safety 137 tolerances of manned aviation, individuals who currently hold Class 138 1/2/3/LAPL certificates should be able to meet the minimum medical 139 standards for UAS operations 140 Unmanned aviation presents a unique opportunity to include people with disabilities where 141 that might not be possible in traditional manned aviation. Inclusivity has been considered 142 throughout our work on the medical standards. As well as the human functional elements 143 of flying remotely, other risks such as pilot incapacitation were also assessed as part of 144 this work in the context of the Command Unit (CU). 145 Based on the research carried out by the CAA Medical Team and reviewed by the 146 RPCWG, the proposal is to use the Light Aircraft Pilots License (LAPL) Medical Certificate 147 minimum standards as a minimum standard to hold the RPC-A competency. 148 The RPC-B will not require a formal medical certificate and will continue to use the 149 declarative fitness to fly methodology. 150 The CAA will continue to review this policy particularly in relation to the increasing use of 151 automation which may result in a custom RP medical certificate being developed in the 152 future. 153 A separate CAP detailing how RPs can take advantage of the LAPL medical certificate system will be published in due course. A supporting CAP will also detail how General 154 155 Practitioners (GPs) will issue LAPL medical certificates for RPs at the same time. 156 157 158 159 160 161 162 163 164 165 166 167 168

# <sup>170</sup> The Future Remote Pilot Competency Framework

#### <sup>171</sup> Introduction

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- 172 The future RP competency framework introduces two core RP competency certificates:
  - The Basic Remote Pilot Certificate or RPC-B
- 174 The Advanced Remote Pilot Certificate or RPC-A

Each RP competency will be divided into two variants; aeroplane (A), where the primary
 source of lift of the aircraft is fixed wings, and rotorcraft (R) where the primary source of lift
 of the aircraft is rotating wings. These variants allow classification of novel and hybrid UAS
 for example a fixed wing VTOL.

- 179 In addition to these new core certificates, the CAA is proposing to introduc
- In addition to these new core certificates, the CAA is proposing to introduce several
   operation specific training certificates that can be added to the RPC-A as part of a modular
   approach.

#### <sup>182</sup> The General VLOS Certificate (GVC)

- 183 The GVC was developed to provide an acceptable means of compliance to Article 8 after184 the introduction of the EU Regulation Package.
- 185 RAEs may continue to provide GVC courses if they wish to. The GVC would remain an
   186 acceptable competency for PDRA-01 however, it will be not automatically be accepted for
   187 any new PDRAs adopted by the CAA, depending on the operational requirements.
- The CAA recognises RP and operator investment in training and will introduce a credit
   system to consider previous training in final RP competency policy.
- <sup>190</sup> The CAA is keen to hear feedback on the retaining the GVC as a basic level of VLOS
- <sup>191</sup> training or phasing it out after the introduction of the new competency framework
- <sup>192</sup> detailed in this document.
- 193
- 194
- 195
- 196

#### <sup>197</sup> The Basic Remote Pilot Certificate (RPC-B)

#### <sup>198</sup> Introduction

The RPC-B is designed to train RPs with the competencies to fly more complex operations
 including BVLOS subject to the operator's operational authorisation.

A revised theorical knowledge assessment has been developed to focus on a broader
 range of operations than the GVC. The fundamentals of BVLOS flying are also covered to
 account for potential future PDRA competency requirements.

- The most significant difference between the GVC and the RPC-B is the required minimum
   flight instruction. The proposed minimum requirements are:
  - 5 hours of non-Global Positioning System (GPS) assisted flight instruction
- 5 hours of mission-based flight instruction
- 208 10 hours of GPS assisted flight instruction

The requirement to be competent in non-GPS assisted flying is safety driven. Intelligence from the CAA and AAIB showed that several accidents were caused by a of a lack of RP training in non-GPS assisted flight modes. The CAA has recognised this and as a result is implementing the above requirement for future RPs.

- The requirement to be competent in mission-based flying is a result of increased use of
  automation in routine UAS operations. Most UAS now have a mission based (GPS
  Waypoint) flying mode. Mission based flying represents a different and important skill for
  RPs. Competency in mission-based flying will help to prepare RPs for real world
  operations.
- The requirement to complete mandatory GPS assisted flight instruction is designed to
  improve the overall standard of RP competency. The CAA recognises that RAE practical
  flight instructors possess a huge amount of valuable experience however, the GVC affords
  very little time to pass on that knowledge. This requirement will increase knowledge
  transfer, improve standards, and RP preparedness for PDRA operations.
- 223

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#### 224 Privileges and Conditions

225 The detailed privileges and conditions of the RPC-B can be found in <u>Appendix A</u>

226

## Advanced Remote Pilot Certificate (RPC-A)

#### <sup>229</sup> Introduction

- The RPC-A is designed to prepare RPs for complex UAS operations in the Specific category including BVLOS.
- The RPC-A consists of a new extended theorical knowledge assessment criteria and minimum flight instruction requirements. Details of the proposed extended theoretical assessment criteria can be found in Appendix B.
- The initial RPC-A minimum flight instruction and assessment criteria have been developed using a task analysis (available in Appendix C) and competency analysis according to established ICAO best practise. A list of recommended competencies is available in (Appendix D).
- The delivery of complex UAS training will be challenging requiring sufficient knowledge, resources, and internal oversight procedures.

#### 241 Privileges and Conditions

242 The detailed privileges and conditions of the RPC-A can be found in Appendix B

#### <sup>243</sup> Complex Operations Training Modules

#### <sup>244</sup> Introduction

- As described in Chapter 1, the CAA has identified that the following operations may need specific RP competency training:
- BVLOS in Controlled Airspace
- Arriving and departing from licensed aerodromes
- Complex BVLOS in a multicrew/distributed crew operation
- Flying highly automated UAS
- UA Swarming operations
- Flying multiple simultaneous operations (MSO)

#### <sup>253</sup> Privileges and Conditions

The CAA is developing the minimum requirements for these modules and proposals will be communicated in the future for consultation.

#### The CAA is very keen to hear feedback and opinion on the proposed additional modules above as part of bringing forward a detailed structure.

#### <sup>258</sup> CHAPTER 3

# <sup>259</sup> Appendix A - The Basic Remote Pilot Certificate

260 261 262 263 264	Note – for the purposes of brevity, aeroplane and rotorcraft subject matter has been combined in this document however, it will be separated in the final policy e.g., RPC-B(A) and RPC-B(R). If you have feedback regarding a specific variant, please mark your response accordingly.
265	General Conditions and Privileges
266 267	Applicants for the issue of an RPC-B shall have fulfilled the requirements of the relevant training course at a CAA approved RAE
268 269	The RP shall have completed the following initial training prior to being accepted for further training:
270 271	<ul> <li>Open category online training material (AMC1UAS.OPEN.20(4)(b) &amp; UASOPEN.040(3) &amp; UASOPEN.0302(a)</li> </ul>
272	<ul> <li>Open category online assessment, and have obtained a Flyer ID.</li> </ul>
273	Proposed RPC-B Privileges
274 275	The privileges of the holders of an RPC-B are to act as RP in command or flight crew of UAS including for renumeration where:
276	the flight is being undertaken in the Specific category
277	and
278 279	<ul> <li>a PRDA has been released by the CAA which states that an RPC-B is an acceptable means of competency</li> </ul>
280	or
281 282	<ul> <li>has been identified a by the operator as the necessary level of competency as set out in UAS.SPEC.050(1)(d)(i).</li> </ul>
283	Credit for Previous Training
284 285 286	The CAA recognises the previous investment RPs have made in training such as the GVC. However, this needs to be balanced against the future RP competency standards which

will enable access to more complex operations.

- <sup>287</sup> The CAA is proposing that holders of a valid GVC at the time of entry to training will
- receive up to a 20% reduction in the GPS flight instruction element of the RPC-B. RAEs
- will be empowered to exercise judgment as to the individual reduction, for example based
   on a pre-entry test and on a case-by-case basis.

#### <sup>291</sup> Currency and Refresher Training

- The CAA is planning to introduce a digital record of competency for every registered RP.
   The system will be administered jointly by the CAA and RAEs.
- Holders of an RPC-B will submit currency logs to the CAA on yearly basis. The minimum
   currency at any time shall be no less than two hours on type within the last 90 days or less
   depending on the policy of the UAS Operator.
- RPC-B will require renewal by an RAE every three years including an assessment for
   mandatory refresher training. Further details of this will be made available in the future.

#### <sup>299</sup> The RPC-B Theory Assessment Topics

- 300 Theoretical knowledge will be assessed via multiple choice examination with a minimum
- 301 number of questions per subject area. The aviation standard pass mark of 75% will be 302 used for all examinations.
- 303 Table 1 RPC-B Theoretical Assessment Topics

Item	RPC-B Theoretical Knowledge Topics	
1	Air La	aw
	1.1	Demonstrate an understanding of the UK Regulation (EU) 2019/947 with particular attention to articles describing the responsibilities of RPs and UAS Operators
	1.2	Demonstrate an understanding of the Acceptable Means of Compliance to UK Regulation (EU) 2019/947 including relevant CAA supporting publications
	1.3	Demonstrate awareness of the UK Air Navigation Order including residual articles relevant to UAS operations
	1.4	Demonstrate an understanding of the Operational Authorisation (OA) and how it describes the privileges and conditions it sets out
	1.5	Demonstrate an understanding of operational risk management methodologies accepted by the CAA in the UK including: i. PRDAs and their published risk assessments ii. the principles of SORA operating safety cases
2	Airsp	ace Operating Principles
	2.1	Describe specific airspace classifications and types.
	2.2	Describe the UK airspace reservations such as: i. Danger Areas ii. Restricted Areas iii. Prohibited areas
	2.3	Demonstrate an understanding of official sources of information that support UAS operations
	2.4	Extract information from relevant aeronautical information sources
	2.5	Interpret information from aeronautical information sources for their applicability to UAS operations
3	Airma	anship and Aviation Safety

Item	RPC	-B Theoretical Knowledge Topics
	3.1	Demonstrate an understanding of good RP competency principles and how
		these principles and situational awareness are linked
	3.2	Demonstrate an awareness of safety management systems (SMS) and the role
		of the RP in maintaining an SMS
	3.3	Demonstrate an awareness of emergency response plan (ERP) procedures
		and the role of the RP in maintaining an ERP
	3.4	Demonstrate an awareness of good and bad organisational safety culture
		including the principles of just culture.
	3.5	Describe the importance of mandatory occurrence, AAIB, airprox and aviation
	0.0	reporting systems and their role in aviation safety
	3.6	Demonstrate the ability to create a mandatory occurrence report (MOR) via the
	5.0	
	27	relevant reporting channel
4	3.7	Demonstrate an awareness of other reporting types
4	Hum	nan Factors
	4.1	Describe how human performance (and thus flight safety) is affected by:
		i. fatigue
		ii. RP fitness to fly
	4.2	Describe limitations humans have in using systems with differing designs of:
		i. ground station aircraft controls
		ii. data entry methodologies
		iii. interpretation of flight and map display information
		iv. warnings, cautions and routine messages
	4.3	Recognise human behaviours that can both positively and negatively affect the
	4.5	safety of the flight, to include:
		i. threat and error management (TEM)
		ii. crew resource management, maintain effective communications
		situational awareness
		iii. decision making
		iv. automation induced complacency
5	Mete	eorology
	5.1	Demonstrate ability to obtain, interpret and apply meteorological reports and
	0.1	forecasts for operations
	5.2	Describe potentially adverse weather conditions and their effects on the UA
	5.3	
	5.5	Demonstrate an understanding of meteorological terminology such as units of
0		
6	1	measurement
Ŭ	Instr	measurement ruments, Navigation and Communication
	Instr 6.1	
	6.1	uments, Navigation and Communication Explain the principles of operation and performance limitations of GPS
		uments, Navigation and Communication
	6.1	uments, Navigation and Communication Explain the principles of operation and performance limitations of GPS
	6.1 6.2 6.3	Explain the principles of operation and performance limitations of GPS Describe GPS errors and the source of these errors Explain the need and process for GPS integrity and continuity checking
	6.1 6.2	Explain the principles of operation and performance limitations of GPS Describe GPS errors and the source of these errors
	6.1 6.2 6.3	Explain the principles of operation and performance limitations of GPS Describe GPS errors and the source of these errors Explain the need and process for GPS integrity and continuity checking
	<ul><li>6.1</li><li>6.2</li><li>6.3</li><li>6.4</li><li>6.5</li></ul>	uments, Navigation and CommunicationExplain the principles of operation and performance limitations of GPSDescribe GPS errors and the source of these errorsExplain the need and process for GPS integrity and continuity checkingReserved for futureDemonstrate an understanding of the flight instruments on an UAS
	6.1 6.2 6.3 6.4	Fuments, Navigation and Communication         Explain the principles of operation and performance limitations of GPS         Describe GPS errors and the source of these errors         Explain the need and process for GPS integrity and continuity checking         Reserved for future         Demonstrate an understanding of the flight instruments on an UAS         Describe how the following UAS systems work:
	<ul><li>6.1</li><li>6.2</li><li>6.3</li><li>6.4</li><li>6.5</li></ul>	Tuments, Navigation and Communication         Explain the principles of operation and performance limitations of GPS         Describe GPS errors and the source of these errors         Explain the need and process for GPS integrity and continuity checking         Reserved for future         Demonstrate an understanding of the flight instruments on an UAS         Describe how the following UAS systems work:         i.       UAS automation
	<ul><li>6.1</li><li>6.2</li><li>6.3</li><li>6.4</li><li>6.5</li></ul>	uments, Navigation and Communication         Explain the principles of operation and performance limitations of GPS         Describe GPS errors and the source of these errors         Explain the need and process for GPS integrity and continuity checking         Reserved for future         Demonstrate an understanding of the flight instruments on an UAS         Describe how the following UAS systems work:         i.       UAS automation         ii.       altimetry instruments and their limitations
	<ul><li>6.1</li><li>6.2</li><li>6.3</li><li>6.4</li><li>6.5</li></ul>	uments, Navigation and Communication         Explain the principles of operation and performance limitations of GPS         Describe GPS errors and the source of these errors         Explain the need and process for GPS integrity and continuity checking         Reserved for future         Demonstrate an understanding of the flight instruments on an UAS         Describe how the following UAS systems work:         i.       UAS automation         ii.       altimetry instruments and their limitations         iii.       C2 link technologies
	<ul><li>6.1</li><li>6.2</li><li>6.3</li><li>6.4</li><li>6.5</li></ul>	uments, Navigation and Communication         Explain the principles of operation and performance limitations of GPS         Describe GPS errors and the source of these errors         Explain the need and process for GPS integrity and continuity checking         Reserved for future         Demonstrate an understanding of the flight instruments on an UAS         Describe how the following UAS systems work:         i.       UAS automation         ii.       altimetry instruments and their limitations

Item	RPC	-B Theoretical Knowledge Topics
		vi. surveillance equipment/technologies
		vii. instruments, telemetry, and display systems
	6.7	Describe the effects of:
		i. distance and obstacles between the transmitter and receiver on the
		quality of the C2 link
		ii. electromagnetic interference from various sources on the strength and
		quality of the C2 link signal
		iii. environmental factors such as weather, dust, precipitation, and cloud
		on system performance
	6.8	Describe the rules applicable to UAS regarding operating at or near
		aerodromes, aircraft landing areas and helicopter landing sites
	6.9	Determine if a flight may proceed based on route, aircraft equipment,
		power/fuel available and equipment
7	UAS	Technical Knowledge
	7.1	Describe the basic principles of flight for aeroplanes and rotorcraft
	7.2	Describe the operating principles of common UAS propulsion systems
	7.3	Demonstrate an awareness of common onboard navigation system sensors
		and their performance limitations including:
		i. Compass
		ii. Inertial Measurement Unit (IMU)
		iii. Barometer
		iv. Pitot Tube
		v. Antenna
		vi. GPS Receiver
		vii. DAA
	7.4	Demonstrate an awareness of common command and control link systems
		and their performance limitations
	7.5	Demonstrate an awareness of C2 link frequency and spectrum licencing
		including the role of OFCOM in issuing such licences
	7.6	Demonstrate an awareness of aircraft technical logs
	7.7	Demonstrate the ability to locate, retrieve and interpret aircraft technical logs
		prior to conducting flight operations
	7.8	Demonstrate an awareness of aircraft minimum UA functional requirements for
		go no-go decision making
	7.9	Demonstrate the ability to calculate aircraft mass and balance based on
		manufacturer data
	7.10	Demonstrate an understanding of battery handling procedures
	7.11	Demonstrate an understanding of high-voltage aircraft system safety
		procedures
8	Aviat	ion Security
	8.1	Describe the responsibilities of the RP relating to the security of UAS
		operations
	8.2	Describe the security threats and mitigations that a RP may encounter when
		flying including:
		i. Cyber threats
		ii. Physical threats
	8.3	Demonstrate an awareness of the relevant UK privacy regulations and the
		General Data Protection Regulation

#### <sup>305</sup> **Practical Flight Assessment**

#### 306 General

An applicant for a skill test for the RPC-B shall have received instruction on the same classor type of UAS to be used in the test.

309 An applicant shall pass all the relevant sections of the skill test. If any item in a section is

failed, that section is failed. Failure in more than one section will require the applicant to

- take the entire test again. An applicant failing only in one section shall only repeat thefailed section. Failure in any section of the retest, including those sections that have been
- 313 passed on a previous attempt, will require the applicant to take the entire test again. All
- 314 relevant sections of the skill test shall be completed within 6 months. Failure to achieve a
- pass in all relevant sections of the test in two attempts will require further training.
- Further training may be required following any failed skill test. There is no limit to the number of skill tests that may be attempted.

#### <sup>318</sup> Conduct of the test

- 319 Should the applicant choose to terminate a skill test for reasons considered inadequate by
- 320 the Flight Examiner (FE), the applicant shall retake the entire skill test. If the test is
- 321 terminated for reasons considered adequate by the FE, only those sections not completed322 shall be tested in a further flight.
- 323 At the discretion of the FE, any manoeuvre or procedure of the test may be repeated once
- by the applicant. The FE may stop the test at any stage if it is considered that the
- 325 applicant's demonstration of flying skills requires a complete re-test.
- An applicant shall indicate to the FE the checks and duties carried out. Checks shall be
- 327 completed in accordance with the checklist for the aircraft on which the test is being taken.328 During pre-flight preparation for the test, the applicant will configure the (CU).
- The FE shall take no part in the operation of the aircraft except where intervention is necessary in the interests of safety.

#### <sup>331</sup> Content of the skill test for the issue of an RPC-B

- The UAS used for the skills test shall meet the requirements for training UAS as set out in the relevant CAA publication.
- The skills test shall comprise of two parts and shall be carried out as real-world practicalflying:
- Part A, a general handling examination in a range of flight modes including non positioning mode lasting a minimum of 30 minutes
- 338 **and**
- 339 Part B a waypoint mission-based examination including a flight segment where the340 UAS is to be flown beyond visual line of sight (BVLOS).

#### 341 RPC-B PART A

- 342 Use of checklists, situational awareness, control of the aeroplane/rotorcraft either manually
- or by use of the CU, and principles of risk management apply to all sections.

#### 344 Table 2 - RPC-B Skills Test Part A

	test for the issue of an RPC-B Part A Required for Aeroplanes   R = Required for Rotorcraft	A	R
Sec	tion – 1 Pre Flight		
	Conducts a pre-flight, including flight planning, documentation, mass and balance consideration, flight briefing, NOTAMS	•	•
1.2	Aeroplane/rotorcraft inspection and servicing	•	•
1.3	Take-off	•	٠
1.4	Take-off uneven ground		٠
1.5	Performance considerations	•	•
Sec	tion – 2 General Handling		
2.1	<ul> <li>Control of the aeroplane/rotorcraft by use of the CU on both positioning and non-positioning flight modes including:</li> <li>1) level flight, control of heading, altitude, and airspeed</li> <li>2) climbing and descending turns</li> <li>3) recoveries from unusual attitudes</li> </ul>	•	•
2.2	Flight at critically low airspeeds including recognition of and recovery from stalls	•	
2.3	Turns, including turns in landing configuration. Steep turns 45°	•	
2.4	Flight at critically high airspeeds	•	
2.5	Hover Manoeuvres (if applicable)		٠
2.6	Autorotation (if equipped)		٠
Sec	tion – 3 Approach and Landing		
4.1	Approach procedures	•	٠
4.3	Go-around action from low height	•	٠
4.4	Normal Landing	•	•
4.5	Post flight actions	•	•
Sec	tion - 4 Abnormal and Emergency Procedures		
	Simulated engine failure	•	•
5.2	Equipment malfunctions	•	٠
5.3	Forced landing (simulated)	•	•
5.4	Oral questions	•	•

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#### 352 RPC-B PART B

- 353 Use of checklists, situational awareness, control of the aeroplane/rotorcraft either manually
- or by use of the CU, and principles of risk management apply to all sections.

#### 355 Table 3 - RPC-B Skills Test Part B

	l test for the issue of an RPC-B Part B Required for Aeroplanes   R = Required for Rotorcraft	A	R
	tion – 1 Pre Flight Operations		
1.1		•	٠
1.2	Configures the CU	•	•
	Aeroplane/rotorcraft inspection and servicing	•	•
1.4	Take-off	•	٠
1.5	Performance considerations	•	٠
Sec	tion – 2 Infight procedures		
2.1	Control of aeroplane/rotorcraft by the CU, including mission configuration and range/endurance considerations	•	•
2.2	Monitoring of flight progress, fuel/energy usage, airspace, and ground risks	•	•
2.3	Altitude, speed, heading control	•	•
2.4	Monitoring navigation and communication system performance	•	•
2.5	CU management	•	•
	tion – 3 Approach and Landing		
	Approach procedures	•	•
4.3	Go-around action from low height	•	•
	Normal Landing	•	•
	Post flight actions	•	•
Sec	tion – 4 Abnormal and Contingency Procedures		
5.1	5	•	•
	Equipment malfunctions	•	٠
	Forced landing (simulated)	•	•
5.4	Oral questions	•	•

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# <sup>361</sup> CHAPTER 4 <sup>362</sup> Appendix B – The Advanced Remote Pilot Certificate

Note – for the purposes of brevity, aeroplane and rotorcraft subject matter has been combined in this document however it will be separated in the final policy e.g. RPC-

365 A(A) and RPC-A(R). If you have feedback regarding a specific variant, please mark

366 your response accordingly.

#### 367 Minimum age

368 Applicants for an RPC-A shall be at least 18 years old

#### 369 General Conditions and Privileges

- 370 Applicants for the issue of an RPC-A shall have fulfilled the requirements of the relevant
- 371 training course at a CAA approved RAE

#### 372 Training course

- 373 Applicants for an RPC-A shall complete a practical training course at an RAE
- 374 The course shall include theoretical knowledge and flight instruction appropriate to the
- 375 privileges of the RPC-A Certificate
- 376 Theoretical knowledge instruction and flight instruction may be completed at a RAE
- 377 different to the one where applicants have commenced their training

#### 378 Remote Pilot Certificate RPC-A

- 379 Entry to training
- Before being accepted for training an applicant should be informed that the appropriatemedical certificate must be obtained.
- The RP shall have completed the following initial training prior to being accepted for further training:
- Open category online training material (AMC1UAS.OPEN.20(4)(b) & UASOPEN.040(3) & UASOPEN.0302(a)
  - Open category online assessment, and have obtained a Flyer ID.

#### 387 Privileges

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- The privileges of the holders of an RPC-A are to act as RP in command or flight crew of a UA including for renumeration where:
  - the flight is being undertaken in the Specific Category

392 393	<ul> <li>a pre-defined risk assessment PRDA has been released by the CAA which states that an RPC-A(A) is an acceptable means of competency</li> </ul>	
394	or	
395 396	<ul> <li>has been identified a by the operator as the necessary level of competency as set out in UAS.SPEC.050(1)(d)(i).</li> </ul>	
397	Conditions	
398	Applicants for the RPC-A shall hold the minimum of a LAPL Medical Certificate.	
399	Applicants for the RPC-A shall hold an Advanced UAS Theoretical Certificate.	
400	RPC-A Experience requirements and crediting	
401 402 403	Applicants for the RPC-A(A) shall have completed at least 55 hours of flight instruction using an UAS suitable for complex operations, 35 of which may be completed using a CAA approved Flight Simulator Device including at least:	
404	<ul> <li>35 hours of beyond visual line of sight dual flight simulator instruction; and</li> </ul>	
405	<ul> <li>15 hours of beyond visual line of sight dual practical flight instruction; and</li> </ul>	
406	5 hours practical flight as RP In Command	
407 408	Crediting. Applicants with prior experience as a licenced manned aviation pilot or military pilot may be credited towards the requirements above.	
409 410 411	The amount of credit shall be decided by the RAE where the pilot undergoes the training course, based on a pre-entry flight test, but shall in any case not exceed 10% of the total hours required.	
412 413	The CAA will publish sperate guidance on the use of flight simulator devices for RP training in due course.	
414	Theoretical Assessment Topics	
415 416 417	Theoretical knowledge will be assessed via multiple choice examination with a minimum number of questions per subject area. The aviation standard pass mark of 75% will be used for all examinations.	
418	Note – the CAA may introduce per subject assessments for safety critical topics.	
419	Table 4 - RPC-A Theoretical Assessment Topics	
	Item RPC-A Theoretical Assessment Topics	
	1         Air Law           1.1         Demonstrate an understanding of the UK Regulation (EU) 2019/947 with particular	
	attention to articles describing the responsibilities of RPs and operators	
	1.2         Demonstrate an understanding of the Acceptable Means of Compliance to UK           Regulation (EU) 2019/947 including relevant CAA supporting publications	
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and

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Item		A Theoretical Assessment Topics
	1.3	Demonstrate awareness of the UK Air Navigation Order including residual articles
		relevant to UAS operations
	1.4	Demonstrate awareness of international aviation law relevant to manned and
		unmanned aviation for example ICAO SARPs and other relevant international
		conventions such as SERA
	1.5	Describe the privileges and conditions of the Advanced Remote Pilot Competency
		certificate and published operation specific training modules
	1.6	Describe the currency and recurrency requirements of the Advanced Remote Pilot
		Competency certificate and published operation specific training modules
	1.7	Demonstrate an understanding of the operational authorisation (OA) and how it
		describes the privileges and conditions it sets out
	1.8	Demonstrate an understanding of operational risk management methodologies
		accepted by the CAA in the UK including
		i. PRDAs and their published risk assessment
		ii. the principles of SORA
		iii. operating safety cases
2	Airspa	ace Operating Principles
	2.1	Describe the UK airspace construct including Flight Information Regions and
	2.1	airspace classifications
	2.2	Describe specific airspace types such as Flight Restriction Zones (FRZ) and other
	2.2	controlled airspace zones
	2.3	Describe the UK airspace reservations such as
	2.0	i. Danger Areas
		ii. Restricted Areas
		iii. Prohibited areas
	2.4	Demonstrate an understanding of official sources of information that support UAS
	2.4	operations
	2.5	Extract information from relevant aeronautical information sources
	2.6	Interpret information from aeronautical information sources for their applicability to
		UAS operations
3		nship and Aviation Safety
	3.1	Demonstrate an understanding of good RP competency principles and how these
		principles and situational awareness are linked
	3.2	Demonstrate an awareness of safety management systems (SMS) and the role of
		the RP in maintaining an SMS
	3.3	Demonstrate an awareness of emergency response plan procedures and the role of
		the RP in maintaining an ERP
	3.4	Demonstrate an awareness of good and bad organisational safety culture including
		the principles of just culture
	3.5	Describe the importance of mandatory occurrence reporting
	3.6	Demonstrate the ability to create an MOR via the relevant reporting channel
	3.7	Demonstrate an awareness of other reporting types such as Airprox and CHIRP
4	Huma	n Factors
	4.1	Demonstrate an awareness of the medical standards for each RP competency
		certificate available for specific category UAS operations
	4.2	Describe limitations humans have in using systems with differing designs of:
		i. CU and aircraft controls
		ii. data entry methodologies
		iii. interpretation of flight and map display information
		iv. warnings, cautions and routine messages
	4.3	Describe how human performance (and thus flight safety) is affected by:
		i. fatigue
L	1	

Item	RPC-/	A Theoretical Assessment Topics
		ii. monotonous monitoring of the UAS
	4.4	Recognise human behaviours that can both positively and negatively affect the safety of the flight, to include:
		i. threat and error management (TEM)
		ii. crew resource management, maintain effective communications
		iii. situational awareness
		iv. decision making
	4 5	v. automation induced complacency
	4.5	Demonstrate an awareness of the principles of crew resource management when both co-located with other crew members and remote from other crew members
	4.6	Demonstrate an awareness of multi-crew cooperation procedures and best practices
5	Meteo	prology
	5.1	Demonstrate awareness of how meteorological conditions affect manned aviation for both visual flight rules (VFR) and instrument flight rules (IFR) operations and how this may increase UAS operation threats and errors
	5.2	Demonstrate ability to obtain, interpret and apply meteorological reports and
		forecasts for operations when both co-located with the pilot and remote from the pilot
	5.3	Demonstrate awareness of how weather patterns and surface pressure can change
	<b>F A</b>	over distance and how this will affect the BVLOS operations
	5.4	Describe adverse weather conditions and their effects on the UA
	5.5	Describe flying conditions and the dangers of airframe icing, hail, microbursts, wind shear, turbulence enroute, when experienced in conjunction with certain cloud types, precipitation, temperature, wind, and wake turbulence.
	5.6	Demonstrate an understanding of meteorological terminology such as units of measurement
6	Instru	ments, Navigation and Communication
	6.1	Explain the principles of operation and performance limitations of GPS
	6.2	Describe GPS errors and the source of these errors
	6.3	Explain the need and process for GPS integrity and continuity checking
	6.4	Reserved for future
	6.5	Demonstrate an understanding of the flight instruments on a CU
	6.6	Demonstrate an understanding of navigation equipment that should be installed and serviceable for conducting a BVLOS flight.
	6.7	Describe how the following UAS systems work: i. UA automation
		<ul><li>ii. altimetry instruments and their limitations</li><li>iii. C2 link technologies</li></ul>
		iv. geo-awareness and its limitations
		v. aeronautical communications
		vi. surveillance equipment/technologies
		vii. instruments, telemetry, and display systems
	6.8	Describe the effects of:
		<ul> <li>distance and obstacles between the transmitter and receiver on the quality of the C2 link</li> </ul>
		<li>electromagnetic interference from various sources on the strength and quality of the C2 link signal</li>
		iii. environmental factors such as weather, dust, volcanic ash, precipitation, and cloud on system performance
	•	

6.9         Demonstrate an understanding of tools for situational awareness and monitoring UA flight paths for the purpose of deconfliction           6.10         Demonstrate an understanding of enroute navigation, including navigation to prevent loss of situational awareness of UA location           6.11         State the rules applicable to UA regarding operating at or near aerodromes, aircraft landing areas and helicopter landing sites           6.12         Determine if a flight may proceed based on route, aircraft equipment, power/fuel available and equipment           6.13         Explain how Minimum Safe Altitude (MSA) affects manned aircraft planning and operations for the purpose of deconflicting between manned and remotely piloted aircraft           6.14         Describe strategic planning methods to deconflict remotely UAS from other traffic. terrain, and obstacles           6.15         Identify local, area and aerodrome pressure settings I (QNH/QFE) and the standard pressure setting for the purpose of deconflicting vertically against other traffic.           6.16         Demonstrate ability to plan for operations in proximity to ground risk classes higher than approved for the current operation           6.17         Demonstrate ability to plan for operations in proximity to air risk classes higher than approved for the current operation           6.18         Demonstrate an understanding of aerodrome instrument approach and departure procedures for manned aircraft           6.20         Demonstrate an understanding of raecodrome visual joining and departure procedures for manned aircraft <td< th=""><th>Item</th><th>RPC-A</th><th>A Theoretical Assessment Topics</th></td<>	Item	RPC-A	A Theoretical Assessment Topics
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7.3 Demonstrate an awareness of common onboard navigation system sensors and			
their performance limitations which shall include:		7.3	
			their performance limitations which shall include:

Item	RPC-	A Theoretical Assessment Topics
		i. Compass
		ii. IMU
		iii. Barometer
		iv. Pitot Tube
		v. Antenna
		vi. GPS Receiver
		vii. DAA
	7.4	Demonstrate an awareness of common command and control link systems and
		their performance limitations which shall include:
		i. Radio
		ii. Satellite
		iii. Cellular Network
	7.5	Demonstrate an awareness of common electronic conspicuity systems and their
		performance limitations which shall include:
		i. ADS-B
		ii. FLARM iii. Pilot Aware
	7.6	iv. Other relevant technologies
	7.6	Demonstrate an awareness of C2 link frequency and spectrum licencing including the role of OFCOM in issuing such licences
	7.7	Demonstrate an awareness of airborne VHF radio systems and licencing including
	1.1	the role of OFCOM in issuing such licences
	7.8	Demonstrate an awareness of aircraft technical logs
	7.9	Demonstrate the ability to locate, retrieve and interpret aircraft technical logs prior to conducting flight operations
	7.10	Demonstrate an awareness of aircraft minimum equipment lists
	7.11	Demonstrate the ability to calculate aircraft mass and balance based on
		manufacturer data
	7.12	Demonstrate an understanding of battery handling procedures
	7.13	Demonstrate an understanding of high-voltage aircraft system safety procedures
	7.14	Demonstrate and understanding of aviation fuel handling procedures and relevant health and safety legislation such a COSHH
8	Aviati	on Security
	8.1	Describe the responsibilities of the RP relating to the security of UAS operations
	8.2	Describe the security threats and mitigations that a RP may encounter when flying including: i. Cyber threats ii. Physical threats
	8.3	Demonstrate an awareness of the relevant carriage of dangerous goods regulations
	8.4	Demonstrate an awareness of the relevant UK privacy regulations and GDPR

#### 425 Practical Flight Assessment RPC-A

#### 426 General

427 An applicant for a skill test for the RPC-A shall have received instruction on the same class428 or type of UAS to be used in the test.

429 An applicant shall pass all the relevant sections of the skill test. If any item in a section is

failed, that section is failed. Failure in more than one section will require the applicant totake the entire test again. An applicant failing only in one section shall only repeat the

432 failed section. Failure in any section of the retest, including those sections that have been

433 passed on a previous attempt, will require the applicant to take the entire test again. All

434 relevant sections of the skill test shall be completed within 6 months. Failure to achieve a

435 pass in all relevant sections of the test in two attempts will require further training.

Further training may be required following any failed skill test. There is no limit to thenumber of skill tests that may be attempted.

#### 438 **Conduct of the test**

439 Should the applicant choose to terminate a skill test for reasons considered inadequate by

the Flight Examiner (FE), the applicant shall retake the entire skill test. If the test is

terminated for reasons considered adequate by the FE, only those sections not completedshall be tested in a further flight.

443 At the discretion of the FE, any manoeuvre or procedure of the test may be repeated once

by the applicant. The FE may stop the test at any stage if it is considered that the

445 applicant's demonstration of flying skills requires a complete re-test.

446 Checks shall be completed in accordance with the checklist for the aircraft on which the

test is being taken. During pre-flight preparation for the test, the applicant will configure theCU.

449 The FE shall take no part in the operation of the aircraft except where intervention is

450 necessary in the interests of safety, to avoid unacceptable delay to other traffic, or to avoid451 a collision.

#### 452 Content of the skill test for the issue of an RPC-A

The UAS used for the skill test shall meet the requirements for training UAS as set out in the relevant CAA publication.

The route to be flown shall be chosen by the FE and the destination shall be an

456 uncontrolled aerodrome, private landing site, or final approach and take-off area (FATO).

- 457 After landing at the remote location, the applicant shall arrange the aircraft turn around,
- depart, and return to the initial take-off location. The applicant shall be responsible for the
- 459 flight planning and shall ensure that all equipment and documentation for the execution of
- the flight are correctly completed. The total of both legs of the flight test shall be no less
- than 60 minutes.

- 462 Use of the aeroplane/rotorcraft checklists, control of the aeroplane/rotorcraft by use of the
- 463 CU, and principles of threat and error management apply in all sections. The control of the
- 464 UA and situational awareness will not be in doubt throughout the test exercises.

#### 465 Table 5 - RPC-A Skills Test

Skil	test for the issue of an RPC-A	А	R
A =	Required for Aeroplanes   R = Required for Rotorcraft		
Sec	tion – 1 Pre Flight Operations and Departure		
	Conducts a pre-flight, including Flight planning, Documentation, Mass and	•	٠
	balance consideration, flight brief, NOTAMS		
1.2	Aeroplane/rotorcraft inspection and servicing	•	•
1.3	Taxiing and take-off	•	
1.4	Hover taxi and take-off		•
1.5	Hover Manoeuvres using the CU to position the aircraft		•
1.6	Performance considerations	•	•
1.7	FATO or aerodrome traffic pattern operations	•	•
	Departure procedure, CU configuration, collision avoidance	•	•
	ATC liaison – compliance, R/T procedures	•	•
	tion – 2 General Handling		
2.1	Control of the aeroplane/rotorcraft by use of the CU including:		
	<ol> <li>level flight at various speeds and configurations</li> </ol>		
	2) climbing and descending turns	•	•
	3) recoveries from unusual attitudes		
	4) limited CU panel		
2.2	Flight at critically low airspeeds including recognition of and recovery from	•	
	stalls		
	Turns, including turns in landing configuration. Steep turns 45°	•	
	Turns using up to 30°bank through 180° & 360° left and right		•
	Flight at critically high airspeeds	•	•
	ATC liaison – compliance, R/T procedures	•	•
Sec	tion – 3 En-Route Procedures		
3.1	Control of aeroplane/rotorcraft by the CU, including cruise configuration and	•	•
	range/endurance considerations		
3.2	Monitoring of flight progress, flight log, fuel/energy usage, airspace, and	•	•
	ground risk		
3.3	Altitude, speed, heading control	•	٠
3.4	Observation and interpretation of weather data, assessment of trends,	•	٠
	diversion planning		
	Monitoring navigation and communication system performance	•	•
Sec	tion – 4 Approach and Landing		
4.1	Arrival procedures, altimeter setting, use of checklists	•	•
	ATC liaison - compliance, R/T procedures	•	٠
	Go-around action from low height	•	٠
	Normal Landing	•	٠
4.5	Post flight actions	•	٠
Sec	tion -5 Abnormal and Emergency Procedures		
5.1	Simulated engine failure after take-off (at a safe altitude), fire drill	•	٠
	Equipment malfunctions	•	•
5.3	Forced landing (simulated)	•	
	Autorotation (if applicable)		•
5.5	ATC liaison - compliance, R/T procedures	•	•
5.6	Oral questions	•	•

# <sup>466</sup> CHAPTER 5 <sup>467</sup> APPENDIX C – Training Task Analysis

468 During the development of the RPC-A the CAA conducted a broad RP task analysis in

accordance with ICAO PANS-TRG Doc 9868. This analysis was used to inform our initial
 position in relation to minimum instruction hours, knowledge, skills, and attitudes (KSAs),

- 471 and flight test assessment standards.
- 472 The CAA have taken the decision to publish the task analysis and performance statements
- to foster transparency in our analysis process. **Furthermore, the CAA are keen to hear**
- 474 feedback on the completeness of our analysis based on real world operations.
- 475 After the consultation has concluded the CAA will carry further task analyses capturing
- 476 industry feedback for individual training as required.

#### 477

#### 478 Table 6 - Task Analysis Ground Operations

Flight Phase – Ground Operations	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task - Dispatch Duties		
Subtasks:		
Verifies the technical condition of the aircraft including MEL where applicable	•	•
Checks technical bulletins and notices	•	•
Determines the impact of weather on aircraft performance	•	•
Applies flight planning and loading procedures	•	•
Prepares the flight plan in accordance with operational authorisation	•	•
Primary Task - Fuel/Energy Planning		
Subtasks:		
Determines fuel/energy required for trip in accordance with procedures	•	•
Ensures fuel/energy allowance is sufficient for operational requirements given	•	•
the conditions and factors on the day		
Primary Task - Refuelling		
Subtasks:		
Ensures aircraft is safe to be refuelled	•	•
Handles high voltage batteries in accordance with SOPs	•	•
Ensures that high voltage batteries are secured in accordance with SOPs	•	•
Ensures that fuel is of correct grade and free from contamination	•	•
Ensures that fuel caps are closed and secured after refuelling	•	•
Primary Task – CU Preparation		
Subtasks:		
Completes all checklist items	•	•
Completes setup procedure in accordance with SOP	•	•
Liaises efficiently with all personnel	•	•
Ensures flightworthiness of the aircraft	•	•
Checks take off performance is within operating range	•	•
Primary Task - Start and After Start Procedures	•	•
Subtasks:		

Flight Phase – Ground Operations	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Asks for, receives, acknowledges, and checks ATC clearance	•	•
Completes engine start and after start procedures	•	•
Uses standard communication procedures with ground crew and ATC	•	•
Primary Task - Flight Briefing		
Subtasks:		
Prepares and delivers standard briefing before flight	•	•
Conducts a take-off/emergency briefing	•	•
Conducts a third-party safety briefing	•	•
Primary Task - Taxi		
Subtasks:		
Completes all recommended taxiing checks and procedures	•	•
Complies with aerodrome/FATO markings and signals	•	•
Controls the aircraft/rotorcraft with appropriate usage of the CU	•	•
Follows ATC instructions	•	•
Completes all departure checks and drills	•	•
Obtains ATC departure clearance	•	•
Confirms aircraft performance criteria	•	•
Uses situational awareness tools to avoid ground conflict	•	•
Primary Task - Pre-Take Off Procedures		
Subtasks:		
Performs approved pre-take off checklist	•	•
Requests and complies with ATC clearance or broadcast intensions	•	•
Check approach and runway/FATO are clear	•	•
Configures aircraft for take-off in accordance with appropriate SOP	•	•
Aligns aircraft with runway or FATO	•	•
Performs approved line up checks	•	•
Checks weather on departure route	•	•
Check runway/FATO status and wind	•	●

#### 480 Table 7 - Task Analysis Take Off and Departure

Flight Phase – Take Off and Departure	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task - Take Off		
Subtasks:		
Initiates take off procedure using the CU	•	•
Confirms the propulsion system is within operating limits	•	•
Performs take off procedure in accordance with relevant SOP	•	•
Maintains situational awareness in relation to obstacle clearance	•	•
Ensure safe climb and departure adjusting aircraft configuration as	•	•
appropriate		
Completes all necessary after take-off checks	•	•
Rejects the take-off for abnormalities prior to reaching take off safety speed	•	•
Primary Task - Crosswind Take Off		
Subtasks:		
Calculates crosswind component for departure runway/FATO	•	•
Initiates take off procedure using the CU	•	•
Confirms the propulsion system is within operating limits	•	•
Performs take off procedure in accordance with relevant SOP	•	•
Maintains situational awareness in relation to obstacle clearance	•	•

Flight Phase – Take Off and Departure	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Ensure safe climb and departure adjusting aircraft configuration as	•	•
appropriate		
Completes all necessary after take-off checks	•	•
Rejects the take-off for abnormalities prior to reaching take off safety speed	•	•
Primary Task – Automation Management		
Subtasks:		
Maintains a constant awareness of the aircraft's automation state	•	•
Manages automation to achieve optimum trajectory and minimum workload	•	•
Takes effective recovery and actions from automation anomalies	•	•
Operates the aircraft in its various automatic modes	•	•
Monitors the Flight Mode Annunciators and flight path	•	•
Primary Task – Propulsion Failure after Take Off		
Subtasks:		
Performs immediate actions in accordance with QRH	•	•
Follows the prescribed engine out profile as detailed in the applicable SOP	•	•
Manual		
Advises ATC or any agency capable of aiding, of situation and intensions	•	•
Lands aircraft ensuring safest outcome	•	•
Primary Task – Aborted Take-off		
Subtasks:	•	•
Understands what fault would cause an aborted take-off	•	•
Performs an emergency briefing prior to take-off	•	•
Performs the aborted take-off procedure in accordance with SOPs	•	•
Communicates with ATC and other crew members	•	•
Conducts post aborted take-off actions	•	•

#### 482 Table 8 – Task Analysis Climb Out

Flight Phase – Climb Out	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task – Climbing		
Subtasks:		
Configures the RP station appropriately for desired climb performance demonstrating knowledge of best angle, best rate, and cruise climb	•	•
Sets altimeter in accordance with procedures specified in the appropriate SOP manual and regulatory requirements	•	•
Identifies and avoids terrain and traffic threats	•	•
Anticipates the expected level off altitude and monitors the aircraft effectively	•	•
Maintains and monitors heading	•	•
Monitors and reacts appropriately to engine indications and performance	•	•
Adjusts flight profile for weather en-route	•	•
Primary Task – Climbing Turns		
Subtasks:		
Performs pre-turn situational awareness procedures according to SOPs	•	•
Uses appropriate RP station turn mode	•	•
Turns aircraft at various rates depending on the required turn performance	•	•
Monitors engine performance	•	•
Primary Task – Aerodrome/FATO departure		
Subtasks:		
Uses charts or other published information as required	•	•

Flight Phase – Climb Out	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Executes a safe departure in accordance with published information	•	●
Uses ground situational awareness tools appropriately	•	•
Observes the rules of the air and ATC regulations	•	•
Uses correct R/T phraseology	•	•
Maintains directional control	•	•
Follows approved flight routing considering ground risk and air risk	•	•
characteristics		
Completes all necessary climb checks	•	●
Demonstrates terrain awareness	•	●
Completes departure from the circuit/FATO without incident	•	●
Primary Task - Standard Instrument Departure Procedures		
Subtasks:		
Uses charts, CU displayed data, or other published information as required	•	•
Executes a safe departure in accordance with published information	•	•
Uses ground situational awareness tools appropriately	•	•
Observes the rules of the air and ATC regulations	•	•
Uses correct R/T phraseology	•	•
Maintains directional control	•	•
Follows approved flight routing considering ground risk and air risk	•	•
characteristics		
Completes all necessary climb checks	•	•
Demonstrates terrain awareness	•	•
Completes departure from the circuit/FATO without incident	•	•

#### 484 Table 9 - Task Analysis Cruse

Flight Phase - Cruise	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task - Straight and Level		
Subtasks:		
Sets and maintains throttle/speed appropriately for desired flight performance	•	٠
Maintains altitude within the approved operational tolerance	•	٠
Maintains heading within the approved operational tolerance	•	٠
Primary Task – CU Planned Turns		
Subtasks:		
Monitors CU when approaching planned turn	•	•
Uses effective CU scan technique	•	٠
Communicates turn progress with flight crew members using standard	•	٠
phraseology		
Verifies new heading is as expected	•	•
Maintains situational awareness throughout the turn	•	•
Primary Task – Unplanned Turns		
Subtasks:		
Selects the appropriate CU mode for the manoeuvre	•	•
Programs the CU accurately and efficiently	•	٠
Verifies the turn is within the aircraft performance envelope	•	•
Executes the instruction correctly	•	٠
Verifies the flight path has been updated as expected	•	•
Verifies new heading is as expected	•	•
Maintains situational awareness throughout the turn	•	٠

Flight Phase - Cruise	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Communicates turn progress with flight crew members using standard	•	•
phraseology		
Primary Task – Missed Turn		
Subtasks:		
Recognises missed turn quickly and takes appropriate action	•	•
Selects appropriate CU mode to maintain control	•	•
Uses CU effectively to re-establish on correct heading	•	•
Updates the CU route to correct for resulting deviation	•	٠
Verifies the flight path has been updated as expected	•	٠
Verifies new heading is as expected	•	٠
Maintains situational awareness throughout the turn	•	٠
Communicates turn progress with flight crew members using standard	•	٠
phraseology		
Primary Task – Stalling		
Subtasks:		
Performs pre manoeuvre checks	•	
Recognise and recover from various stalls	•	
Recognises visual and aural stall warning devices while approaching the stall	•	
Recovers from stall with minimum loss of altitude	•	
Adjusts aircraft attitude and power setting to resume normal balanced flight	•	
on advent of stall.		
Primary Task – Practised Forced Landing		
Subtasks:		
Maintains control of the aircraft	•	•
Selects landing area within gliding distance	•	٠
Uses all available situational awareness tools to identify areas of low ground	•	٠
risk		
Performs immediate actions in accordance with QRH	•	•
Makes decision to land immediately as soon as it becomes apparent	•	•
Demonstrates planning, workload management, and communication skills	•	•
during emergency in accordance with procedures		
Performs emergency checks in accordance with QRH	•	•
Advises ATC or any agency that can aid of the situation and intensions	•	•
Uses CU to manoeuvre the aircraft to landing area	•	•
Lands the aircraft ensuring safest outcome if an engine restart is not possible	•	•
Primary Task – Maintenance of Altitude, Heading, and Speed Using the CU		
Subtasks:		
Uses the CU to maintain planned altitude, heading and speed	•	•
Always maintains situational awareness	•	•
Demonstrates awareness of concentration fatigue	•	•
Primary Task – Navigation Procedures		
Subtasks:		
Completes all elements of flight planning for the route prescribed with	•	•
reference to planned altitudes, and safe levels of operation		
Demonstrates a thorough understanding of the approved operational volume	•	•
during the flight		
Primary Task – Managing Fuel/Energy		
Subtasks:		
Manage aircraft fuel/energy state and take appropriate action	•	•
Operates fuel/energy system in accordance with SOP	•	•

Flight Phase - Cruise	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task – Comply with Airspace Requirements		
Subtasks:		
Explains geographical limits of the approved flight area	•	•
Explains the dimensions of the operational volume including flight geography	•	•
and contingency volume		
Explains air risk buffer and adject airspace principles	•	•
Determines the position of controlled airspace using a chart	•	•
Identifies and avoids restricted airspace using a chart	•	•
Primary Task – Traffic Awareness		
Subtasks:		
Uses situational awareness tools effectively	•	•
Maintains radio listening and interprets transmissions to determine traffic location and intensions of traffic	•	•
Primary Task – Single Crew Operations		
Subtasks:		
Uses checklist in appropriate manner	•	•
Makes configuration changes in accidence with SOP	•	٠
Communicates effectively with training staff, crew members and other	•	٠
personnel		
Demonstrates good single crew CRM	•	•
Primary Task – Multi Crew Operations		
Subtasks:		
Uses checklist in appropriate manner	•	•
Makes configuration changes in accordance with SOP	•	•
Communicates effectively with training staff, crew members and other personnel	•	•
Demonstrates good multi crew CRM	•	•
Primary Task – Diversion		
Subtasks:		
Calculates heading, groundspeed, ET A and fuel required during any		
unscheduled diversion.	•	•
Calculates Safety Altitude for track to new destination.	•	٠
Maintains the heading, height and speed	•	٠
Primary Task – Monitor Navigation Accuracy		
Subtasks:		
Demonstrates adequate area/route knowledge	•	٠
Navigates according to CU flight plan and clearance	•	٠
Adjusts flight to weather and traffic conditions	•	٠
Communicates and coordinates with ATC	•	٠
Primary Task – Monitors GPS Navigation System		
Subtasks:		
Determines if aircraft is within rated coverage of station.	•	•
Enters and checks waypoint entry in GPS system.	•	•
Verifies the integrity of GPS signal.	•	•
Primary Task – Flight Management		
Subtasks:		
Completes all necessary checks and drills	•	•
	•	•
Configures airframe and engine(s) for cruise/ endurance performance in accordance with SOP manual		

A = Required for Aeroplanes   R = Required for Rotorcraft Adjusts and monitors fuel/energy consumption for range or endurance as appropriate Sets and cross checks altimeters to QNH, standard pressure setting as specified Maintains effective R/T communications using correct phraseology throughout Obtains ATC clearances and appropriate level of service Adheres to ATC instructions Avoid misunderstandings by requesting clarification Primary Task – CU Management Subtasks: Programs the CU with route specific information in accordance with SOPs Programs the CU with route specific information in accordance with SOPs Cross-checks and seeks confirmation of all relevant information entered Safely operates the CU whilst in flight Modifies the CU data whilst in flight Primary Task – Limited CU Panel Subtasks: Recognises the effect of an engine failure by sight, sound, instrumentation & performance Maintains control of the aircraft by appropriate use of the CU Gathers information and identifies the affected engine Controls the aircraft accurately whilst conducting QRH procedures Understands the relationship between power, attitude & speed Controls the aircraft accurately whilst conducting QRH procedures Understands the relationship between power, attitude & speed Controls the aircraft accurately whilst conducting QRH procedures Understands the effect on the fuel system and takes appropriate action Assesses situation & considers engine restart if appropriate Primary Task – Non-Normal C2 Link Degradation in Flight Subtasks: Recognises link degradation by sound, instruments, and performance Takes latency into account while executing CU commands Controls the aircraft whilst conducting QRH procedures Manages the non-normal situation ensuring a safe outcome Primary Task – Non-Normal C2 Link Failure in Flight Subtasks: Descriptions and interments and a performance Primary Task – Non-Normal C2 Link Failure in Flight Subtasks: Promese fuell descriptions heagend in the flight Primary Task – N	• • • • • • • • • • • • • • • • • • •	• • • •
Sets and cross checks altimeters to QNH, standard pressure setting as specified         Maintains effective R/T communications using correct phraseology throughout         Obtains ATC clearances and appropriate level of service         Adheres to ATC instructions         Avoid misunderstandings by requesting clarification         Primary Task – CU Management         Subtasks:         Programs the CU with route specific information in accordance with SOPs         Programs the CU with performance specific information in accordance with SOPs         Cross-checks and seeks confirmation of all relevant information entered         Safely operates the CU whilst in flight         Modifies the CU data whilst in flight         Primary Task – Limited CU Panel         Subtasks:         Controls the aircraft using limited CU panel         Primary Task – Non-Normal Propulsion Failure in Flight         Subtasks:         Recognises the effect of an engine failure by sight, sound, instrumentation & performance         Maintains control of the aircraft by appropriate use of the CU         Gathers information and identifies the affected engine         Controls the aircraft accurately whilst conducting QRH procedures         Understands the relationship between power, attitude & speed         Controls the aircraft accurately on one engine whilst climbing, descending & turning         Understands the effect on the	• • • • • • • • • • • • • • • • • • • •	•
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Safely operates the CU whilst in flight         Modifies the CU data whilst in flight         Primary Task – Limited CU Panel         Subtasks:         Controls the aircraft using limited CU panel         Primary Task – Non-Normal Propulsion Failure in Flight         Subtasks:         Recognises the effect of an engine failure by sight, sound, instrumentation & performance         Maintains control of the aircraft by appropriate use of the CU         Gathers information and identifies the affected engine         Controls the aircraft accurately whilst conducting QRH procedures         Understands the relationship between power, attitude & speed         Controls the aircraft accurately on one engine whilst climbing, descending & turning         Understands the effect on the fuel system and takes appropriate action         Assesses situation & considers engine restart if appropriate         Primary Task – Non-Normal C2 Link Degradation in Flight         Subtasks:         Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight		•
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Subtasks:       Controls the aircraft using limited CU panel         Primary Task – Non-Normal Propulsion Failure in Flight       Subtasks:         Subtasks:       Recognises the effect of an engine failure by sight, sound, instrumentation & performance         Maintains control of the aircraft by appropriate use of the CU       Gathers information and identifies the affected engine         Controls the aircraft accurately whilst conducting QRH procedures       Understands the relationship between power, attitude & speed         Controls the aircraft accurately on one engine whilst climbing, descending & turning       Understands the effect on the fuel system and takes appropriate action         Assesses situation & considers engine restart if appropriate       Primary Task – Non-Normal C2 Link Degradation in Flight         Subtasks:       Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands       Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome       Primary Task – Non-Normal C2 Link Failure in Flight		
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Subtasks:       Recognises the effect of an engine failure by sight, sound, instrumentation & performance         Maintains control of the aircraft by appropriate use of the CU       Gathers information and identifies the affected engine         Controls the aircraft accurately whilst conducting QRH procedures       Understands the relationship between power, attitude & speed         Controls the aircraft accurately on one engine whilst climbing, descending & turning       Understands the effect on the fuel system and takes appropriate action         Assesses situation & considers engine restart if appropriate       Primary Task – Non-Normal C2 Link Degradation in Flight         Subtasks:       Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands       Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome       Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:       Subtasks:       Subtasks:		
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Gathers information and identifies the affected engine       Controls the aircraft accurately whilst conducting QRH procedures         Understands the relationship between power, attitude & speed       Controls the aircraft accurately on one engine whilst climbing, descending & turning         Understands the effect on the fuel system and takes appropriate action       Assesses situation & considers engine restart if appropriate         Primary Task – Non-Normal C2 Link Degradation in Flight       Subtasks:         Recognises link degradation by sound, instruments, and performance       Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures       Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight       Subtasks:	•	٠
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Understands the relationship between power, attitude & speed         Controls the aircraft accurately on one engine whilst climbing, descending & turning         Understands the effect on the fuel system and takes appropriate action         Assesses situation & considers engine restart if appropriate         Primary Task – Non-Normal C2 Link Degradation in Flight         Subtasks:         Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight	•	٠
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Understands the effect on the fuel system and takes appropriate action         Assesses situation & considers engine restart if appropriate         Primary Task – Non-Normal C2 Link Degradation in Flight         Subtasks:         Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:	•	•
Assesses situation & considers engine restart if appropriate         Primary Task – Non-Normal C2 Link Degradation in Flight         Subtasks:         Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:	•	•
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Subtasks:       Recognises link degradation by sound, instruments, and performance         Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:		
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Takes latency into account while executing CU commands         Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:	•	•
Controls the aircraft whilst conducting QRH procedures         Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:	•	
Manages the non-normal situation ensuring a safe outcome         Primary Task – Non-Normal C2 Link Failure in Flight         Subtasks:	•	
Primary Task – Non-Normal C2 Link Failure in Flight Subtasks:	•	
Subtasks:		
		-
Recognises link degradation by sound, instruments, and performance Conducts QRH procedures	•	•
Manages the non-normal situation ensuring a safe outcome	•	•
Primary Task – Non-Normal Navigation System Failure in Flight (GPS/IMU)		
Subtasks:		
Recognises navigation failure by sound, instruments, and performance	•	-
Conducts QRH procedures		•
Manages the non-normal situation ensuring a safe outcome	•	•
Primary Task – Non-Normal CU Total Failure	_ '	
Subtasks:	-+	
Recognises CU failure		

Flight Phase - Cruise	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Conducts QRH procedures	•	•
Conducts handover to qualified crew member in accidence with SOPs	•	•
Manages the non-normal situation ensuring a safe outcome	•	•

#### 486 Table 10 - Task Analysis Descending

Flight Phase – Descending A = Required for Aeroplanes   R = Required for Rotorcraft	Α	R
Primary Task – Decent Planning		
Subtasks:		
Checks weather of destination and alternate airport		
Checks runway in use/FATO status		
Check MSA and MEA	•	•
Conducts arrival briefing	•	•
	•	•
Primary Task – Descending Subtasks:		
Uses available situation awareness tools prior to descending	•	•
Configures CU to manage power, altitude, and target rate of decent	•	•
Controls aircraft within approved flight envelope	•	•
Sets altimeter in accordance with procedures specified in the appropriate SOP	•	•
Identifies and avoids terrain and traffic threats	•	•
Primary Task – Descending Turns		
Subtasks:		
Uses available situation awareness tools prior to turning	•	•
Configures CU to manage power, bank angle, and rate of turn	•	•
Controls aircraft within approved flight envelope	•	•
Sets altimeter in accordance with procedures specified in the appropriate SOP	•	•
Identifies and avoids terrain and traffic threats	•	•
Primary Task – Emergency Decent		
Subtasks:		
Completes memory items and QRH procedures in accordance with SOPs	•	•
Transmits emergency call to ATC	•	•
Sets safe decent height	•	•
Considers approved ground risk and air risk during decision making	•	•
Closely monitors speed, altitude, and configuration	•	•
Primary Task – Aerodrome/FATO Arrival Procedures		
Subtasks:		
Complies with published arrival procedures	•	•
Sets altimeter and cross checks	•	•
Uses checklists and drills	•	•
Uses correct RT phraseology	•	•
Primary Task – Holding		
Subtasks:		
Interprets hold requirement and programmes CU according to SOPs	•	•
Enters and monitors hold	•	•
Assesses fuel requirements and max hold time	•	•
Primary Task – Aerodrome Rejoin		
Subtasks:		

Flight Phase – Descending	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Complies with published arrival procedure or clearance	•	•
Sets altimeters and cross checks	•	•
Uses checklists and drills	•	•
Uses correct RT phraseology	•	•
Maintains situational awareness	•	•

#### 488 Table 11 - Task Analysis Approach

Approach	Α	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task – Stable Approach		
Subtasks:		
Correctly configures the CU for approach	•	•
Correctly performs relevant checklists	•	•
Correctly applies altimeter settings for the phase of flight	•	•
Performs correct RT procedures	•	•
Correctly identifies and follows airfield approach procedures	•	٠
Primary Task – Missed Approach		
Subtasks:		
Recognises missed approach/landing performance cannot be achieved	•	٠
Uses the CU to configure and execute go-around in accordance with SOPs	•	٠
Performs correct RT procedures	•	•

489

## 490 Table 12 - Task Analysis Landing

Landing	A	R
A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task – Landing		
Subtasks:		
Correctly configures the CU for landing	•	•
Monitors automated landing system via the CU	•	•
Correctly performs relevant checklists	•	•
Correctly applies altimeter settings for the phase of flight	•	•
Performs correct RT procedures	•	•
Touches down at a controlled rate of decent	•	•
Touches down on the runway centreline	•	
Touches down on the centre of designated FATO		•
Performs a safe landing in accordance with SOPs	•	•
Performs post landing checklists	•	•

491 492

#### 493 Table 13 - Task Analysis Post Flight Actions

Post Flight Actions A = Required for Aeroplanes   R = Required for Rotorcraft		
Primary Task – Shutdown		
Subtasks:		
Complies with aerodrome markings and signals	•	•

Post Flight Actions		
A = Required for Aeroplanes   R = Required for Rotorcraft		
Controls the aircraft with use of power and brakes	•	
Follows ATC Instructions	•	•
Follows landing checklist	•	•
Shuts down engine in accordance with SOPs	•	•
Carries out shutdown checklist	•	•
Primary Task – Post Flight Documentation		
Subtasks:		
Communicates with recovery team, ground personnel, and flight crew	•	•
Ensures aircraft is secure and CU is safely disconnected	•	•
Hands over aircraft to ground personnel remotely (land away)	•	•
Completes relevant aircraft documents, reports service issues and completes	•	•
flight/tech logs		

#### 501 CHAPTER 6

## <sup>502</sup> Remote Pilot Competencies

503 The following tables contain recommended RP competencies and observable behaviours 504 in accordance with ICAO PANS-TRG Doc 9868. These competencies could form the basis 505 for the development of RP competency-based training (CBT). **The CAA are keen to hear** 

- 506 feedback on the completeness of these competencies.
- 507

#### 508 Table 14 - Application of Knowledge

#### Application of Knowledge

Description: Demonstrates knowledge and understanding of relevant information, operating instruction, aircraft systems and the operating environment.

#### Observable Behaviours

1 Demonstrates practical and applicable knowledge of limitations and systems and their interactions

2 Demonstrates required knowledge of published operating instructions

3 Demonstrates knowledge of the physical environment, the air traffic environment including routings, weather, airports, and the operational infrastructure

4 Demonstrates appropriate knowledge of applicable legislation

5 Knows where to source required information

6 Demonstrates a positive interest in acquiring knowledge

7 Can apply knowledge effectively

# 509

#### 510

#### 511 **Table 15 - Application of Procedures & Compliance with Regulations**

#### Application of Procedures & Compliance with Regulations

Description: Identifies and applies procedures in accordance with published operating instructions and applicable regulations, using the appropriate knowledge

#### **Observable Behaviours**

- Identifies the source of operating instructions
   Follows standard operating procedures (SOPs) unless a higher degree of safety dictates an appropriate deviation
- 3 Identifies and follows all operating instructions in a timely manner
- 4 Correctly operates the UAS and associated equipment
- 5 Complies with applicable regulations
- 6 Applies relevant procedural knowledge

#### 512

#### 515 Table 16 - Situational Awareness

#### Situational Awareness Description: Perceives and comprehends the operational situation of the moment and all of the relevant information available and anticipates what could happen that may affect the operation Observable Behaviours

1 Identifies and assesses accurately the state of the UAS

- 2 Identifies and assesses accurately the UAS vertical and lateral position, and its anticipated flight path
- 3 Identifies and assesses accurately the general environment as it may affect the flight, including the air traffic neighbouring the UAS operation and the meteorological conditions that could impact the operation
- 4 Conducts the operation in accordance with the airspace configuration where the UAS operation is taking place
- 5 Keeps track of time and energy
- 6 Maintains awareness of the people involved in or affected by the operation and their capacity to perform as expected
- 7 Anticipates accurately what could happen, plans, and stays ahead of the situation
- 8 Develops effective contingency plans based upon potential threats
- 9 Recognizes and effectively responds to indications of reduced situational awareness

#### 516

#### 517 Table 17 - Communication

#### Communication

Description: Demonstrates effective verbal, written and nonverbal communications, in normal and abnormal situations

#### Observable Behaviours

- 1 Ensures the recipient is ready and able to receive the information
- 2 Selects appropriately what, when how and with whom to communicate
- 3 Conveys messages clearly, accurately, and concisely
- 4 Confirms that the recipient correctly understands important information
- 5 Listens actively and demonstrates understanding when receiving information
- 6 Asks relevant and effective questions Adheres to standard radiotelephony phraseology and procedures
- 7 Accurately reads and interprets required documentation for the operation of UAS
- 8 Accurately reads, interprets, constructs and responds to datalink messages
- 9 Completes accurate reports as required by operating procedures
- 10 Correctly interprets non-verbal communication
- 11 Where applicable, uses eye contact, body movement and gestures that are consistent with and support verbal messages

#### 518

#### 519 **Table 18 - RPA flight path management, automation**

#### RPA flight path management, automation

Description: Controls the RPA flight path through automation, including appropriate use of flight management system(s) and guidance

#### **Observable Behaviours**

1 Controls the RPA through automation with accuracy and smoothness as appropriate to the situation

# RPA flight path management, automation Contains the RPA within the normal flight envelope Maintains the desired flight path during flight using automation Takes appropriate action in case of deviations from the desired RPA trajectory Selects appropriate level and mode of automation in a timely manner considering phase of flight and workload Effectively monitors automation, including engagement and automatic mode transitions Controls the RPA safely in degraded automation using only the relationship between RPA attitude, speed and thrust if applicable

#### 520

#### 521 Table 19 - Leadership, teamwork, and self-management

Lea	dership, teamwork, and self-management
Des	cription: Demonstrates effective leadership, team working and self-management
Obs	ervable Behaviours
1	Understands and agrees with the crew's roles and objectives
2	Creates an atmosphere of open communication and encourages team participation
3	Uses initiative and gives directions when required
4	Admits mistakes and takes responsibility for own performance, detecting and resolving own errors
5	Anticipates and responds appropriately to other crew members' needs
6	Carries out instructions when directed
7	Communicates relevant concerns and intentions
8	Gives and receives feedback constructively
9	Confidently intervenes when important for safety
10	Demonstrates empathy and shows respect and tolerance for other people
11	Engages others in planning and allocates activities fairly and appropriately according to abilities
12	Addresses and resolves conflicts and disagreements in a constructive manner
13	Demonstrates self-control in all situations
14	Self-evaluates the effectiveness of actions

522

#### 523 Table 20 - Problem solving and decision making

#### Problem solving and decision making

Description: Accurately identifies risks and resolves problems. Uses the appropriate decisionmaking processes

#### **Observable Behaviours**

1 Seeks accurate and adequate information from appropriate sources

2 Identifies and verifies what and why things have gone wrong

3 Employs proper problem-solving strategies

- 4 Perseveres in working through problems without reducing safety
- 5 Uses appropriate and timely decision-making processes
- 6 Identifies and considers options effectively

Pr	oblem solving and decision making
7	Monitors, reviews and adapts decisions as required
8	Identifies and manages risks and threats to the safety of the UAS and people effectively
9	Changes behaviour and responds as needed to deal with the demands of the changing situation

#### 525

#### 526 Table 21 - Workload management

#### Workload management

Description: Manages available resources efficiently to prioritize and perform tasks in a timely manner under all circumstances

Ob	Observable Behaviours	
1	Plans, prioritizes, and schedules tasks effectively	
2	Manages time efficiently when carrying out tasks	
3	Offers and accepts assistance, delegates when necessary and asks for help early	
4	Reviews, monitors, and crosschecks actions conscientiously	
5	Verifies that tasks are completed to the expected outcome	
6	Manages and recovers from interruptions, distractions, variations and failures effectively	